Frontiers of Statistics: Contraction theory for posterior distributions Spring 2019 Lecture 2: February 21

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**Note**: LaTeX template courtesy of UC Berkeley EECS dept & CMU's convex optimization course taught by Ryan Tibshirani.

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## 2.1 Recap: Hypothesis testing and error rates (Lecam-Birge)

Let  $y_1, \ldots, y_n \stackrel{iid}{\sim} p$  where p is a probability density function. If we consider the following simple null vs. simple alternative testing problem

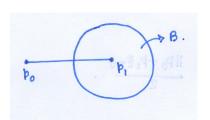
$$H_0: p = p_0$$
 vs.  $H_1: p = p_1$ , (2.1)

then Theorem 1.1 shows that there exists a test function  $\Phi_n$  such that it has exponentially decaying upper bounds to the Type-I and Type-II error probabilities; that is,

$$\mathbb{E}_{p_0} \Phi_n < e^{-Cnh^2(p_0, p_1)} \tag{2.2}$$

$$\mathbb{E}_{p_1}[1 - \Phi_n] \le e^{-Cnh^2(p_0, p_1)}.$$
(2.3)

## 2.2 Extension to testing: Simple null vs. composite alternative



Assume the same setup as above. Now consider the following testing problem:

$$H_0: p = p_0 \quad \text{vs.} \quad H_1: p \in B,$$
 (2.4)

where  $B = \{p \mid ||p - p_1||_{_{\text{TV}}} \leq ||p - p_1||_{_{\text{TV}}}/2\}$  (there is nothing special about the '2' in the denominator; can be any positive number greater than 1). It can be shown that B is a convex set.

**Theorem 2.1.** Under the described setup in 2.2, there exists a test function  $\Phi_n$  such that

$$\mathbb{E}_{p_0} \Phi_n \le e^{-n\|p-p_1\|_{\rm TV}^2/8} \tag{2.5}$$

$$\sup_{p \in B} \mathbb{E}_p[1 - \mathbf{\Phi}_n] \le e^{-n \|p - p_1\|_{\mathrm{TV}}^2/8}.$$
(2.6)

*Proof.* Let

$$\phi(y) = \begin{cases} 1 & \text{if } p_1(y) > p_0(y) \\ 0 & \text{o.w.} \end{cases}$$

Define

$$\alpha = \mathbb{E}_{p_0} \phi(y_1)$$
, and  $\gamma = \inf_{p \in B} \mathbb{E}_p \phi(y_1).$  (2.7)

 $\alpha$  and  $\gamma$  are the Type-I error probability and the minimum power based on one observation. Note that,  $\alpha$  and  $\gamma$  can also be rewritten as follows:

$$\alpha = \int_{p_1 > p_0} p_0 \, d\lambda \tag{2.8}$$

$$\gamma = \inf_{p \in B} \int_{p_1 > p_0} p \, d\lambda \tag{2.9}$$

where  $\lambda$  denotes the dominating measure.

Claim:  $\gamma > \alpha$ . That is, the test  $\phi$  is unbiased.

Proof of claim: Fix  $p \in B$ . Then,

$$\int_{p_1 > p_0} p \, d\lambda = \int_{p_1 > p_0} p_1 \, d\lambda - \int_{p_1 > p_0} (p_1 - p) \, d\lambda \tag{2.10}$$

$$\geq \int_{p_1 > p_0} p_1 \, d\lambda \, - \, \left\| p_1 - p \right\|_{\rm TV} \tag{2.11}$$

$$\geq \int_{p_1 > p_0} p_1 \, d\lambda \, - \, \frac{\|p_1 - p_0\|_{\mathrm{TV}}}{2} \tag{2.12}$$

which does not depend on p. Therefore,

$$\gamma - \alpha = \inf_{p \in B} \left[ \int_{p_1 > p_0} p \, d\lambda - \int_{p_1 > p_0} p_0 \, d\lambda \right]$$
(2.13)

$$= \inf_{p \in B} \left[ \int_{p_1 > p_0} p_1 \, d\lambda \, - \, \frac{\|p_1 - p_0\|_{\mathrm{TV}}}{2} \, - \, \int_{p_1 > p_0} p_0 \, d\lambda \right] \tag{2.14}$$

$$= \|p_1 - p_0\|_{_{\rm TV}}/2 > 0 \tag{2.15}$$

Hence the proof of the claim.  $\blacksquare$ 

## Back to main proof:

Define,

$$\mathbf{\Phi}_n = \begin{cases} 1 & \text{if } \frac{1}{n} \sum_{i=1}^n \phi(y_i) > \frac{\alpha + \gamma}{2} \\ 0 & \text{o.w.} \end{cases}$$

**Theorem 2.2.** Hoeffding's inequality. Suppose  $X_1, \dots, X_n$  are independent random variable such that  $X_i \in [0,1]$ . Then, for any t > 0

$$\Pr\left[\frac{1}{n}\sum_{i=1}^{n} (X_i - \mathbb{E}X_i) > t\right] \le e^{-2nt^2}.$$
(2.16)

Note: This can be thought of as a finite sample version the CLT.

Using this theorem,

$$\mathbb{E}_0 \Phi_n = \mathcal{P}_0 \left[ \frac{1}{n} \sum_{i=1}^n \phi(y_i) > \frac{\alpha + \gamma}{2} \right]$$
(2.17)

$$= P_0 \left[ \frac{1}{n} \sum_{i=1}^n (\phi(y_i) - \mathbb{E}_0 \phi(y_i)) > \frac{\gamma - \alpha}{2} \right]$$
(2.18)

$$\leq e^{-2n(\gamma-\alpha)^2/2} = e^{-n\|p_1-p_0\|_{\rm TV}^2/8}$$
(2.19)

For proving (2.6), fix  $p \in B$ . Then

$$\mathbb{E}_p(1-\boldsymbol{\Phi}_n) = \mathbf{P}_p\left[\frac{1}{n}\sum_{i=1}^n \phi(y_i) < \frac{\alpha+\gamma}{2}\right]$$
(2.20)

$$= \mathbf{P}_p \left[ \frac{1}{n} \sum_{i=1}^n (\phi(y_i) - \mathbb{E}_p \, \phi(y_i)) > \frac{\alpha + \gamma}{2} - \mathbb{E}_p \, \phi(y_1) \right]$$
(2.21)

$$\leq \mathbf{P}_p\left[\frac{1}{n}\sum_{i=1}^n(\phi(y_i) - \mathbb{E}_p\,\phi(y_i)) > \frac{\alpha - \gamma}{2}\right]$$
(2.22)

$$\leq e^{-n\|p_1 - p_0\|_{\mathrm{TV}}^2/8},\tag{2.23}$$

which does not depend on p. This completes the proof of the theorem.

## 2.3 Posterior consistency

Let  $X_1, \ldots, X_n \stackrel{iid}{\sim} P$  where P is a probability measure (or model) and suppose  $X_i$ 's are defined on  $(\Omega, \mathscr{A}, P)$ .  $X^{(n)} := (X_1, \ldots, X_n)$  are defined on  $(\Omega^n, \mathscr{A}^n, P^n)$  as  $X_i$ 's are independent. Let  $\mathscr{P}$  denotes the class of all probability measures.

**Quantity of interest:** P . We further assume that P admits a density p.

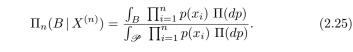
**True density:**  $p_0$ , distribution  $P_0$  (the true data generating density).

Let d denotes a distance metric on  $\mathscr{P}$ , and  $\Pi$  a prior on  $\mathscr{P}$ . Define

$$B(p_0,\varepsilon) := \{ p \mid d(p_0, p) < \varepsilon \}, \tag{2.24}$$

a ball around  $p_0$  of radius  $\varepsilon$ .

For any subset of densities B (that is,  $B \subseteq \mathscr{P}$ ), define the posterior as



**Definition:** Posterior consistency.  $\Pi_n$  is said to be consistent at  $p_0$  if for every  $\varepsilon > 0$ 

$$\Pi_n \left[ B(p_0, \varepsilon) \,|\, X^{(n)} \right] \to 1 \quad \text{in } ? \tag{2.26}$$

There are two notions of convergence; namely,

- (i) "Weak consistency" if the above convergence happens 'in probability (i.p.)' under  $p_0$ .
- (ii) "Strong consistency" if the above convergence happens 'almost surely (a.s.)' under  $p_0$ .

*Remark*: (i) and (ii) implies  $\Pi_n(\cdot | X^{(n)}) \xrightarrow{d} \delta_{\{p_0\}}$  a.s. or i.p. under  $p_0$ .

Posterior consistency for parameterized densities. Suppose the density p considered in the above setup is parameterized by  $\theta \in \Theta$ ; that is,  $p \equiv p_{\theta}$ .

*Example 1.*  $X_1, \ldots, X_n \stackrel{iid}{\sim} N(\mathbf{0}, \Sigma)$ . In this case  $\theta = \Sigma$ .

*Example 2.*  $X_1, \ldots, X_n \stackrel{iid}{\sim} N(\boldsymbol{\mu}, \mathbf{I})$ . In this case  $\theta = \boldsymbol{\mu}$ .





Now the *d* should be considered as a distance metric on  $\Theta$  and  $\Pi$  is a prior on  $\Theta$ . We can similarly define a ball of radius  $\varepsilon$  around  $\theta_0$  as

$$B(\theta_0, \varepsilon) := \{ \theta \in \Theta \, | \, d(\theta_0, \theta) < \varepsilon \}.$$
(2.27)

Then  $\Pi_n$  is said to be consistent at  $\theta_0$  if

$$\Pi_n \left[ B(\theta_0, \varepsilon) \,|\, X^{(n)} \right] \to 1 \qquad \text{a.s. or i.p. under } p_{\theta_0}. \tag{2.28}$$

**Properties of point estimators.** Suppose  $X_1, \ldots, X_n \stackrel{iid}{\sim} p_{\theta}$  (true value of  $\theta$  is  $\theta_0$ ).

**Goal**: To come up with "point estimators"  $\hat{\theta}_n$  depending on the posterior such that  $d(\hat{\theta}_n, \theta) \to 0$  a.s. or i.p. under  $p_{\theta_0}$ . If

$$\hat{\theta}_n = \int \theta \,\Pi_n(d\theta \,|\, X^{(n)}),\tag{2.29}$$

then under additional assumptions apart from posterior consistency,  $d(\hat{\theta}_n, \theta) \to 0$ .

**Theorem 2.3.** Alternative point estimate. Suppose  $\Pi_n(\cdot | X^{(n)})$  is consistent at  $\theta_0$  (with respect to (wrt) d on  $\Theta$ ). Let  $\hat{\theta}_n$  be the center of the smallest ball in d that contains posterior mass at least 1/2. That is,

$$\hat{\theta}_n = \operatorname*{arg\,min}_{\theta \in \Theta} \hat{r}_n(\theta) \tag{2.30}$$

where  $\hat{r}_n(\theta) = \inf\{r \mid \Pi_n(B(\theta, r) \mid X^{(n)}) \ge 1/2\}$ . Then  $d(\hat{\theta}_n, \theta) \to 0$  as  $n \uparrow \infty$  a.s. (or i.p.) wrt  $p_{\theta_0}$ .

*Proof.* Fix  $\varepsilon > 0$ . Then consistency of  $\Pi_n(\cdot | X^{(n)})$  is at  $\theta_0$  implies that there exists  $n_0 \equiv n_0(\varepsilon) \in \mathbb{N}$  such that

$$\Pi_n(B(\theta_0,\varepsilon) \mid X^{(n)}) \ge 1/2 \qquad \forall \ n \ge n_0$$
(2.31)

a.s. wrt  $p_{\theta_0}$ . So by definition of  $\hat{r}_n(\theta)$ , we get  $\hat{r}_n(\theta_0) < \varepsilon$  for all  $n \ge n_0$  a.s. wrt  $p_{\theta_0}$ . Further, by definition of  $\hat{\theta}_n$  we also get

$$\hat{r}_n(\hat{\theta}_n) \le \hat{r}_n(\theta_0) < \varepsilon. \tag{2.32}$$

 $d(\hat{\theta}_{n}, \theta_{o})$  $B(\hat{\theta}_{n}, \hat{\pi}_{n}(\hat{\theta}_{n}))$  $\hat{\theta}_{n}$  $\hat{\pi}_{n}(\hat{\theta}_{n})$ B(Do, Jun (D) Ju (00)

Now let us focus on the two balls  $B(\hat{\theta}_n, \hat{r}_n(\hat{\theta}_n))$  and  $B(\theta_0, \hat{r}_n(\theta_0))$  centered around  $\hat{\theta}_n$  and  $\theta_0$ , respectively. Because of the consistency condition of  $\Pi_n(\cdot | X^{(n)})$  at  $\theta_0$ , the two balls should overlap. Therefore, using (2.33) this implies that

$$d(\hat{\theta}_n, \theta) \le \hat{r}_n(\hat{\theta}_n) + \hat{r}_n(\theta_0) < 2\varepsilon \qquad \forall \ n \ge n_0$$
(2.33)

a.s. wrt $p_{\theta_0}.$  Since  $\varepsilon$  is arbitrary this completes the proof.