

$$i) Y_t = g(x_t) + \varepsilon_t \quad \varepsilon_t \sim N(0, \sigma^2) \quad x_t \text{ has density } f_x$$

we (falsely) fit the model $Y_t = \beta x_t + \varepsilon_t$ [$\varepsilon_t \sim N(0, \sigma^2)$]
to the data.

$$(a) \hat{\beta} = \frac{\sum Y_t X_t}{\sum X_t^2}$$

(ii) By the continuous mapping theorem we have

$$\hat{\beta} = \frac{\frac{1}{T} \sum Y_t X_t}{\frac{1}{T} \sum X_t^2} \rightarrow \frac{E(Y_t X_t)}{E(X_t^2)} = \frac{\int g(x) x f(x) dx}{\int g x^2 f(x) dx} =: \beta_0$$

(iii) There are 2 ways to approach the problem.

Either consider the marginal distribution of Y_t for both the correct model and the best fitting linear model or consider the joint distribution of (Y_t, X_t) for both the best fitting and correct model.

In the case of the marginal distributions the true density is:

$$h(y) = \int \phi[y - g(x)] f_x(x) dx \quad \leftarrow \text{standard normal density}$$

the best fitting is:

$$f_{\beta_0}(y) = \int \phi[y - \beta_0 x] f_x(x) dx.$$

The KL-criterion is then $\mathbb{E}_n \left[\log \frac{f_{\beta}(y)}{h(y)} \right]$, however (2)

it does not give an interesting explicit expression.

Let us, instead, consider the joint distributions.

The true joint distribution is

$$f_{y|x}(y) f_x(x) = \mathcal{L}_{\varepsilon}(y - g(x)) f_x(x)$$

The best fitting distribution is

$$f_{y|x}(y) f_x(x) = \mathcal{L}_{\varepsilon}(y - \beta_0 x) f_x(x).$$

Thus the KL-criterion is

$$\mathbb{E} \left\{ \log \frac{\mathcal{L}_{\varepsilon}(y - \beta x) f_x(x)}{\mathcal{L}_{\varepsilon}(y - g(x)) f_x(x)} \right\}$$

$$= \mathbb{E} \left\{ -\frac{1}{2\sigma^2} (y - \beta x)^2 + \frac{1}{2\sigma^2} (y - g(x))^2 \right\}$$

$$= \frac{1}{2\sigma^2} \int (\beta x - g(x))^2 f(x) dx$$

↑

[after some calculation

and using that

$$\mathbb{E}(YX) = \mathbb{E}(g(X)X)]$$

This has a rather nice form. It will always be negative (as theory tells us), but the better the approximation the closer it will be to zero.

2) let us suppose that Y_t is a discrete r.v. and

X_t are regressors which we know to influence Y_t . If we treat

X_t as random, then conditional on X_t we have

$$\mathbb{E}(Y_t | X_t) = e^{\beta X_t} \text{ and } \text{var}(Y_t | X_t) = e^{\beta X_t} [1 + \xi e^{\beta X_t}], \text{ where}$$

$\xi \geq 0$. The estimating equation.

$$g(\beta) = \sum_t (Y_t - e^{\beta X_t}) X_t = 0 \text{ is used to estimate } \beta.$$

We denote this estimate as $\hat{\beta}$.

By the delta method we have

$$\sqrt{T}(\hat{\beta} - \beta) \mapsto N(0, V_T).$$

(i) $V_T = A_T^{-1} B_T A_T^{-1}$, where

$$A_T = \mathbb{E} \left\{ \frac{1}{T} \sum_t e^{\beta X_t} X_t^2 \right\} = \mathbb{E} \{ e^{\beta X_t} X_t^2 \}$$

$$B_T = \text{var} \left\{ \frac{1}{\sqrt{T}} \sum_t (Y_t - e^{\beta X_t}) X_t \right\} \\ = \frac{1}{T} \sum_t \mathbb{E} \left\{ \text{var}(Y_t - e^{\beta X_t} | X_t) X_t^2 \right\}$$

Since $\mathbb{E}[(Y_t - e^{\beta X_t}) X_t] = 0$

$$= \frac{1}{T} \sum_t \mathbb{E} \left\{ X_t^2 e^{\beta X_t} [1 + \xi e^{\beta X_t}] \right\} \\ = \mathbb{E} [X_t^2 e^{\beta X_t}] + \xi \mathbb{E} [X_t^2 e^{2\beta X_t}]$$

(ii) To derive explicit expressions for A_T and B_T when

X_t are standard normal distributions, we use the

identity:

$$\begin{aligned} \frac{1}{\sqrt{2\pi}} \int x e^{\sigma x} e^{-\frac{1}{2}x^2} dx &= \frac{e^{\sigma^2/2}}{\sqrt{2\pi}} \int x e^{-\frac{1}{2}(x-\sigma)^2} dx \\ &= e^{\sigma^2/2} \left\{ \frac{1}{\sqrt{2\pi}} \int (x-\sigma) e^{-\frac{1}{2}(x-\sigma)^2} dx + \frac{\sigma}{\sqrt{2\pi}} \int e^{-\frac{1}{2}(x-\sigma)^2} dx \right\} \\ &= e^{\sigma^2/2} [0 + \sigma] = \sigma e^{\sigma^2/2} \end{aligned} \quad (1)$$

$$\begin{aligned} \frac{1}{\sqrt{2\pi}} \int x^2 e^{\sigma x} e^{-\frac{1}{2}x^2} dx &= \\ e^{\sigma^2/2} \left[\frac{1}{\sqrt{2\pi}} \int (x-\sigma)^2 e^{-\frac{1}{2}(x-\sigma)^2} dx + \frac{2\sigma}{\sqrt{2\pi}} \int x e^{-\frac{1}{2}(x-\sigma)^2} dx - \frac{\sigma^2}{\sqrt{2\pi}} \int e^{-\frac{1}{2}(x-\sigma)^2} dx \right] \\ &= e^{\sigma^2/2} [1 + \sigma^2] \end{aligned} \quad (2)$$



Thus

$$A_T = \int e^{\beta x_t} x^2 \phi(x) dx = e^{\beta^2/2} (\beta^2 + 1) \quad (\text{by (1)})$$

$$\begin{aligned} B_T &= \mathbb{E}[x_t^2 e^{2\beta x_t}] + \frac{1}{2} \mathbb{E}[x_t^2 e^{2\beta x_t}] \\ &= e^{\beta^2/2} (1 + \beta)^2 + \frac{1}{2} e^{(2\beta)^2/2} [1 + (2\beta)^2] \end{aligned} \quad (3)$$

(iii) Estimate B_T with $\frac{1}{T} \sum_{t=1}^T [(y_t - e^{\beta x_t}) x_t]^2 = \hat{B}$

Given the estimate of $\hat{\beta}$

using

$$\hat{\beta} = e^{\hat{\beta}^2/2} (1 + \hat{\beta}^2)^e + \xi e^{(2\hat{\beta})^2/2} (1 + (2\hat{\beta})^2)^e \quad (5)$$

now we can solve for ξ , to obtain an estimate of ξ .

There also exists graphical methods for estimating ξ too.

3) we have the survival likelihood;

(6)

$$L_T(\theta) = \sum_i \delta_i \log f(T_i; \theta) + \sum_i (1 - \delta_i) \log F(Y_i; \theta).$$

(a) Since the observations are not taking expectations give

$$E\{L_T(\theta)\} = \pi E\{\log f(T_i; \theta)\} + (1 - \pi) E\{\log F(Y_i; \theta)\}$$

since δ_i and (T_i, C_i) are independent.

Differentiating $E\{\log f(T_i; \theta)\}$ wrt θ it is easily seen

$$\text{that } E \frac{\partial E\{\log f(T_i; \theta)\}}{\partial \theta} = 0 \text{ at } \theta = \theta_0.$$

we now consider the term $E\{\log F(Y_i; \theta)\}$ and show that

(usually) the derivative will not equal zero at $\theta = \theta_0$.

First we need the density of Y_i . since $Y_i = \min(T_i, C_i)$

we see that

$$\begin{aligned} P\{\min(T_i, C_i) \leq y\} &= 1 - P\{\min(T_i, C_i) > y\} \\ &= 1 - F(y; \theta_0) G(y) \end{aligned}$$

Thus the density of Y_i is

$$f(y; \theta_0) G(y) + F(y; \theta_0) g(y).$$

→ density of C_i

Using the above we have

$$E\{\log F(y_i; \theta)\} = \int [\log F(y; \theta)] \{f(y; \theta_0)G(y) + F(y; \theta_0)g(y)\} dy \quad (7)$$

To check whether the above is maximum at θ_0 we diff the above w.r.t θ to give

$$\frac{\partial}{\partial \theta} E\{\log F(y_i; \theta)\} = \int \frac{1}{F(y; \theta)} \frac{dF(y; \theta)}{d\theta} \{f(y; \theta_0)G(y) + F(y; \theta_0)g(y)\} dy$$

At the true parameter θ this gives

$$= \underbrace{\int \frac{\partial}{\partial \theta} \int \frac{F(y; \theta)}{F(y; \theta)} g(y) dy}_{=0 \text{ since } \int g(y) dy = 1} + \underbrace{\int \frac{dF(y; \theta)}{d\theta} \frac{G(y)}{F(y; \theta)} f(y; \theta_0) dy}_{\neq 0}$$

$= 0$ since $\int g(y) dy = 1$

Actually $\neq 0$! Yours truly got it wrong! - we all make mistakes 😊

The term will not = 0 (in general).

Thus we have that

$$\frac{dE\{L_T(\theta)\}}{d\theta} \Big|_{\theta=\theta_0} = \underbrace{\pi \frac{dE\{\log f(Y_i; \theta)\}}{d\theta} \Big|_{\theta=\theta_0}}_{=0} + \underbrace{(1-\pi) \frac{dE\{\log F(Y_i; \theta)\}}{d\theta}}_{\text{not necessarily } = 0}$$

Since the derivative of expectation of the criterion is not zero at the true parameter θ_0 , the estimator $\hat{\theta}_T$ is unlikely to consistently estimate θ_0 . It will be a biased (in probability) estimator.

Give my huge mistake, stinky that

(7a)

$$\frac{\partial}{\partial \theta} \int \mathcal{F}(y; \theta) g(y) dy = 0 \quad [\text{not quite sure what come over me}]$$

(x)

The derivation of the unbiasedness

$$\mathbb{E} \left[\frac{-\partial^2 \mathcal{L}_T}{\partial \theta^2} \right] = \mathbb{E} \left[\frac{\partial \mathcal{L}_T}{\partial \theta} \right]^2 \quad \text{is under the assumption.}$$

You should try and see where this derivation falls apart, when (x) is not true!

So I made a huge mistake but it is good practice for you to understand where things work and do not work.

(ii) Now we consider the special case that $G(x) = F(x; \theta_0)$. In this case the density of (2)

$\min(T_i, C_i)$ is $2 f(x; \theta_0) F(x; \theta_0)$. Now by

substituting this into the calculations in (i) it can

be seen that
$$\frac{\partial E[\log F(Y_i; \theta)]}{\partial \theta} \Big|_{\theta = \theta_0} = 0.$$

Thus in this special case the estimator will be consistent.

(iii). Taking second derivatives of

$$\pi E[\log f(T_i; \theta)] + (1-\pi) E[\log f(Y_i; \theta)]$$

gives

$$\pi E \left\{ -\frac{1}{f(T_i; \theta)^2} \left(\frac{\partial f}{\partial \theta} \right)^2 + \frac{1}{f(T_i; \theta)} \frac{\partial^2 f}{\partial \theta^2} \right\}$$

$$+ (1-\pi) E \left\{ -\frac{1}{f(Y_i; \theta)^2} \left(\frac{\partial f(Y_i; \theta)}{\partial \theta} \right)^2 + \frac{1}{f(Y_i; \theta)} \frac{\partial^2 f(Y_i; \theta)}{\partial \theta^2} \right\}$$

Under the assumptions on the distribution given in (ii)

$$E \left\{ \frac{1}{f(Y_i; \theta)} \left(\frac{\partial^2 f(Y_i; \theta)}{\partial \theta^2} \right) \right\} = 0.$$

Thus, if $g(x) = F(x; \theta_0)$ we have

(9)

$$\begin{aligned} & \mathbb{E} \left[\frac{\partial^2}{\partial \theta^2} \left[\pi \mathbb{E} [\log f(T; \theta)] + (1-\pi) \mathbb{E} [\log F(Y; \theta)] \right] \right] \\ &= \pi \mathbb{E} \left[\frac{-1}{f(T; \theta)^2} \left(\frac{\partial f}{\partial \theta} \right)^2 \right] + (1-\pi) \mathbb{E} \left[\frac{-1}{F(Y; \theta)} \left(\frac{\partial F(Y; \theta)}{\partial \theta} \right)^2 \right] \\ &= - \mathbb{E} \left[\frac{\partial}{\partial \theta} \left[\delta_i \log f(T; \theta) + (1-\delta_i) \log F(Y; \theta) \right] \right]^2. \end{aligned}$$

Thus the limiting distribution of the estimator $\hat{\theta}$ (based on the survival likelihood) is

$$\sqrt{T} (\hat{\theta} - \theta_0) \rightarrow N(0, I_1),$$

where

$$I_1 = \pi \mathbb{E} \left[\frac{1}{f(T; \theta)^2} \left(\frac{\partial f}{\partial \theta} \right)^2 \right] + (1-\pi) \mathbb{E} \left[\frac{1}{F(Y; \theta)} \left(\frac{\partial F(Y; \theta)}{\partial \theta} \right)^2 \right].$$

(iv) An alternative method is to maximise the 'non-censored' part of the density, which is

$$\mathcal{L}_2(\theta) = \sum_i \delta_i \log f(T_i; \theta).$$

The limiting distribution of this estimator is

$$\sqrt{T} (\hat{\theta}_2 - \theta_0) \rightarrow N(0, I_2), \text{ where}$$

$$I_2 = \pi \mathbb{E} \left\{ \frac{1}{f(T; \theta)^2} \left(\frac{\partial f}{\partial \theta} \right)^2 \right\}.$$

(10)

We can easily see that $I_1 > I_2$, thus the limiting variance of $\hat{\theta}_1$ is smaller than $\hat{\theta}_2$. Hence in the special case that $G(x) = F(x; \theta)$, it makes sense to use the survival likelihood to estimate θ_0 .